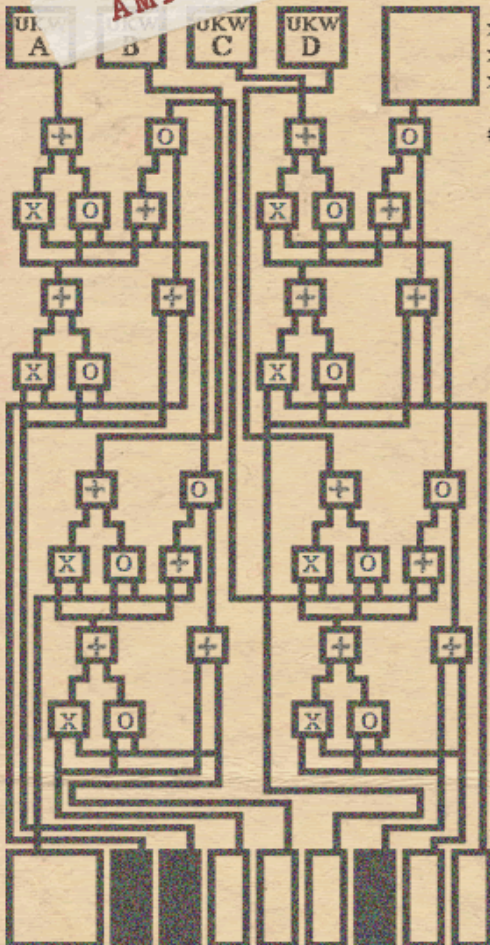


**KHHFV YRIJT ZTCJN XYPOJ XJFYJ  
 EWCGH YJGZC ZMMJC HYXDS BGFLE  
 BEEUW ULBYC JVQDL JMUJA  
 AMRKY ORYCF KUACB QOBDL Y**

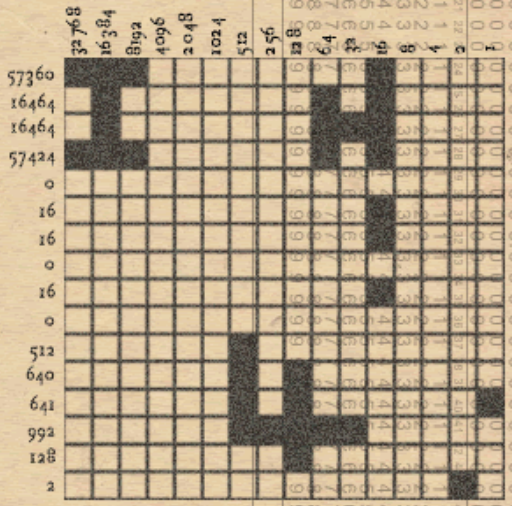
# PLEMENT TO Object R2ode



- > Punchcard Alphabet /3 = 10 + 11 + 12
- > Binary signal ON black OFF non-black [overlay] order 1,2,3 for item 3,2,1
- > Logic Gate and or not and on reflection, should change.

## no plug adjustments required

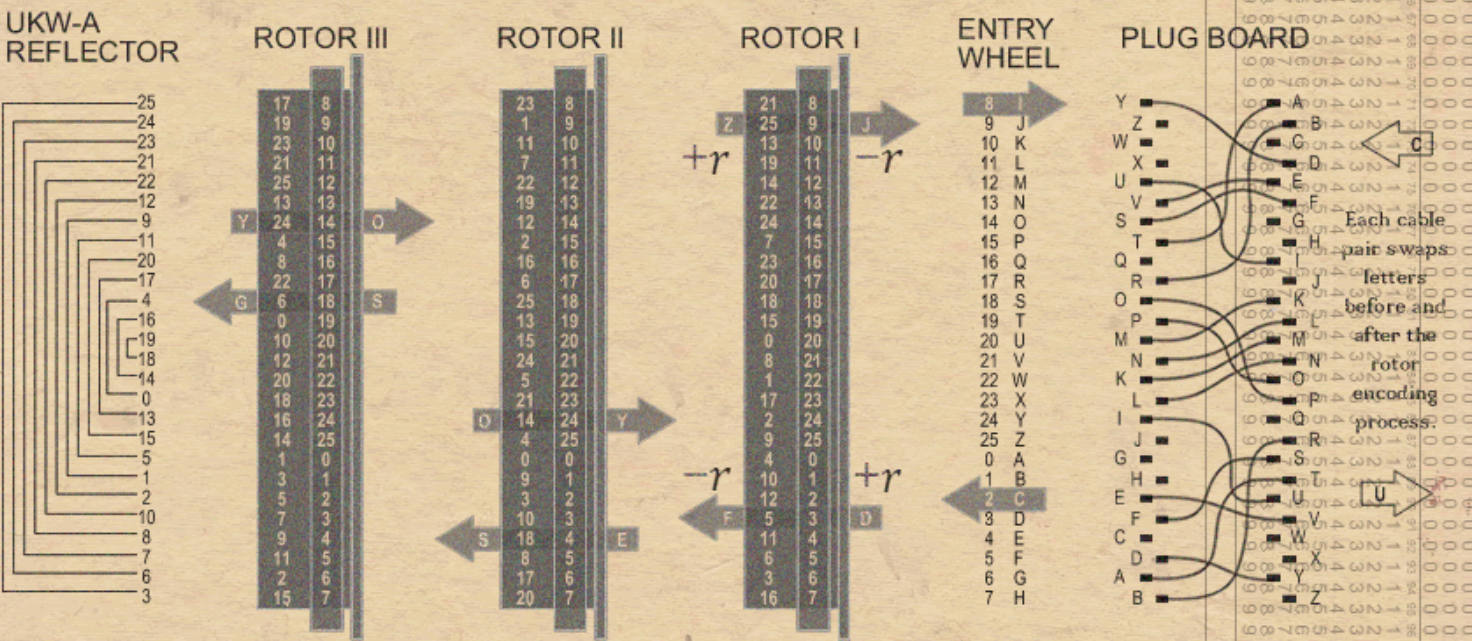
57344	10	TDERR
16512	28	QYTQW
17280	81	QUWIF
57984	98	TUOIR
720	08	UWP
704	800	UPR
704	49085	TIPRI
720	88041	QUQOO
704	40141	QUPOP
720	84085	TIPYY
208	404	WOT
80	024	IP
84	48645	TUREP
21	08241	QYRPW
85	21591	QYRYI
16	44845	TUEYT



	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X	Y	Z
ROTOR I	E	K	M	F	L	G	D	Q	V	Z	N	T	O	W	Y	H	X	U	S	P	A	I	B	R	C	J
ROTOR II	A	J	D	K	S	I	R	U	X	B	L	H	W	T	M	C	Q	G	Z	N	P	Y	F	V	O	E
ROTOR III	B	D	F	H	J	L	C	P	R	T	X	V	Z	N	Y	E	I	W	G	A	K	M	U	S	Q	O
ROTOR IV	F	S	O	V	P	Z	I	A	Y	Q	U	I	R	H	X	L	N	F	T	G	K	D	C	M	W	B
ROTOR V	V	Z	B	R	G	I	T	Y	U	P	S	D	N	H	L	X	A	W	M	J	Q	O	F	E	C	K
UKW A	E	J	M	Z	A	L	Y	X	V	B	W	F	C	R	Q	U	O	N	T	S	P	I	K	H	G	D
UKW B	Y	R	U	H	Q	S	L	D	P	X	N	C	O	K	M	I	E	B	F	Z	C	W	V	J	A	T
UKW C	F	V	P	J	I	A	O	Y	E	D	R	Z	X	W	G	C	T	K	U	Q	S	B	N	M	H	L
UKW D	M	O	W	J	Y	P	U	X	N	D	S	R	A	I	B	F	V	L	K	Z	G	Q	C	H	E	T

U S E  
 C C Y M K A N R F I R G P G H X H J O J T Y W D C U U S Q N D O X D N S A L G I

Signal is sent through plug board, changes letter if applicable, then the three rotors (right to left). The reflector reverses the signal path, returning it through the three rotors (left to right) - excluding offset steps accounting for rotor rotations.



**Important:** First rightmost rotor advances one position after each letter, following a complete rotation (25 rotations), rotor resets to zero the rotor in second position advances by one, with third far left rotor advancing after 25 rotations of rotor in second position. Unlike the rotors, the reflector will not advance its progression. To account for a rotor advancing, input is offset by adding rotation count, once leaving the rotor, this offset is then deducted.  
 !r  
 r = number of rotor rotations since starting position